

Excursion Set Theory

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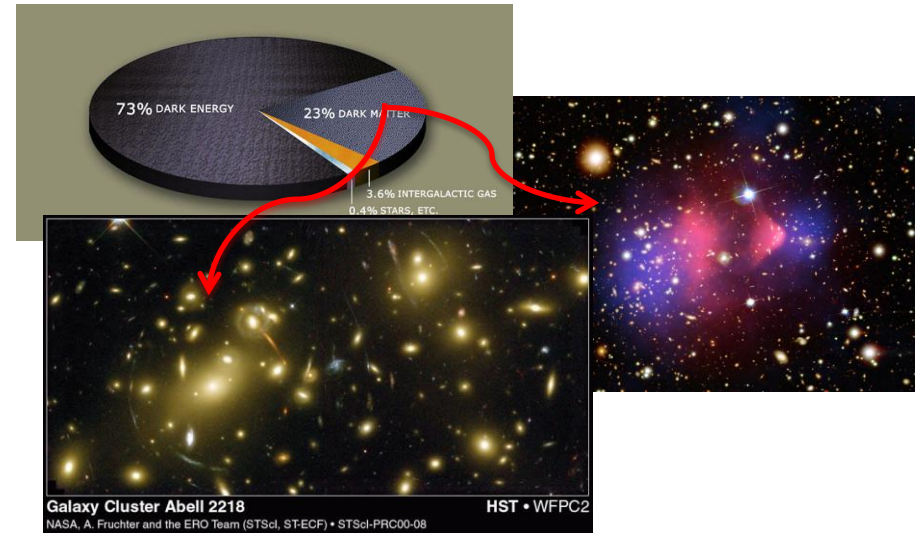
Cosmic Structures and Dark Matter

Dark Matter:

- Foster matter clustering
- Resides in virialized clumps

The Role of Halos:

- Building blocks of cosmic structure formation
- Shape baryon distribution



Halo Properties & Mass Function:

- Statistics of the initial density field
- Non-linear gravitational collapse
- Nature DM particles
- Underlying cosmology

Numerical N-body Simulations Results:

- Collisionless Particle Algorithms (CDM)
- Still require theoretical understanding

$$f(\sigma) = A \left[\left(\frac{\sigma}{b} \right)^{-a} + 1 \right] e^{-c/\sigma^2}$$

Outline

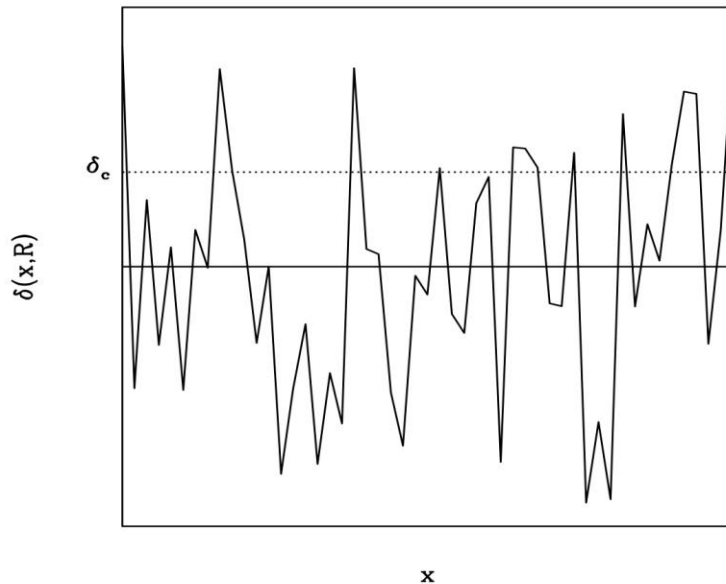
- Press-Schechter Formalism
- The Excursion Set Theory
- Halo Collapse Model
- Halo Mass Definition & Non-Markovianity
- Path-Integral Approach
- Comparison with N-body results

Reference List

- Bond et al., ApJ 379, 440 (1991)
- Sheth, Mo & Tormen, MNRAS 323, 1 (2001)
- Percival, MNRAS 327, 1313 (2001)
- Maggiore & Riotto, ApJ 711, 907 (2010)
- Maggiore & Riotto, ApJ 717, 515 (2010)
- Maggiore & Riotto, ApJ 717, 526 (2010)
- De Simone, Maggiore & Riotto, MNRAS 412, 2587 (2011)
- Ma et al., MNRAS 411, 2644 (2011)
- Corasaniti & Achiouv, PRL 106, 241302 (2011)
- Corasaniti & Achiouv, PRD 84, 023009 (2011)

Press-Schechter Formalism

Halo Mass Distribution & Linear Density Field:



- Filtering scale and mass

$$M = \bar{r} V(R)$$

- Statistics of the smoothed density field

$$P(d, R)$$

- Linearly extrapolated collapse threshold

$$d_c$$

- Fraction of mass in halos $> M$

$$F_{PS}(R[M]) = \int_{d_c}^{\infty} dd P(d, R[M])$$

- #-halos with mass dM

$$\frac{dn}{dM} = \frac{1}{V} \frac{dF}{dM}$$

Press-Schechter Mass Function

Gaussian Field:

- Variance of the smoothed field

$$S^2(R) \propto \int k^2 P(k) |\tilde{W}(k, R)|^2 dk$$

- PDF $P(d, S[R]) = \frac{1}{\sqrt{2\rho S[R]}} e^{-d^2/2S[R]}$

- Spherical collapse threshold d_c

- Fraction of mass in halos

$$F_{PS}(R) = \int_{d_c}^{\infty} dd P(d, S[R]) = \frac{1}{2} \operatorname{Erfc}\left(\frac{d_c}{S(R)\sqrt{2}}\right)$$

- Halo Mass Function

$$\frac{dn}{dM} = \frac{\bar{r}}{M^2} \frac{d \ln S^{-1}}{d \ln M} f(S) \quad \text{with} \quad f_{PS}(S) = 2S^2 \frac{dF_{PS}}{dS} = \frac{1}{\sqrt{2\rho}} \frac{d_c}{S} e^{-d_c^2/(2S^2)}$$

Cloud-in-Cloud Problem

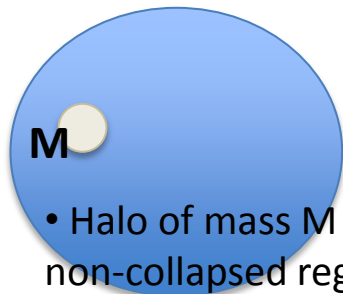
Asymptotic Behavior: • In the limit $R \rightarrow 0$ all mass must be in collapsed structures, $F(0)=1$

- In the PS calculation half of the mass is miscounted

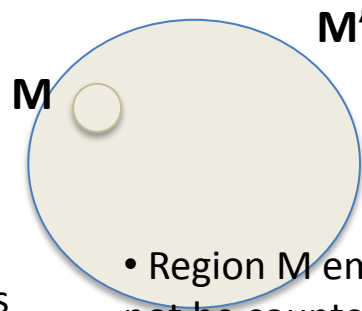
$$F_{PS}(R) = \frac{1}{2} \operatorname{Erfc} \left[\frac{d_c}{S(R)\sqrt{2}} \right] \xrightarrow{R \rightarrow 0} \frac{1}{2}$$

Problem: in the PS approach there is no mass ordering

- No distinction between different configurations (cloud-in-cloud)



- Halo of mass M embedded in a larger non-collapsed region contributes to mass function at mass M

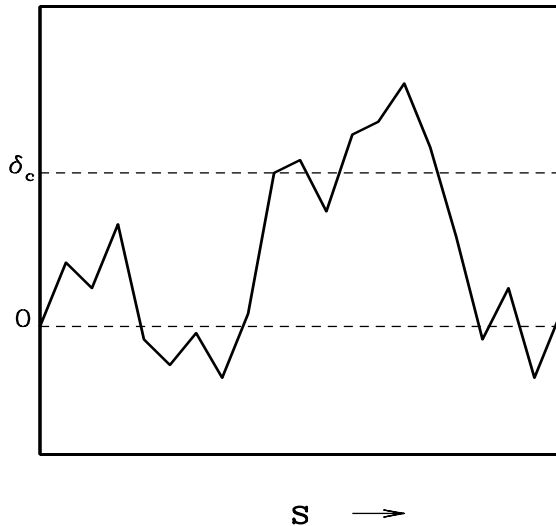


- Region M embedded in halo $M' > M$. M should not be counted in mass function since already included at M'

Excursion Set Theory

$$d(x, R) = \frac{1}{(2\rho)^3} \int d^3 k d(k) \tilde{W}(k, R) e^{-ikx} \quad - \text{At any point } x, \delta \text{ performs a random walk as function of } R$$

- Langevin Equation: $\frac{\partial d}{\partial R} = V(R) \text{ and } V(R) = \frac{1}{(2\rho)^3} \int d^3 k d(k) \frac{\partial \tilde{W}}{\partial R} e^{-ikx}$



- random walks start at $R = \infty$ ($S=0$) with $\delta = 0$ evolving toward smaller R (larger S)
- $\zeta(R)$ depends on $\Pi(\delta)$ and $W(x, R)$
- Halos of mass M corresponds to trajectories crossing the threshold at $S(M)$
- cloud-in-cloud solved by requiring first crossing

Excursion Set Mass Function

Stochastic Problem:

- Computation of the probability distribution of random walks with absorbing boundary, $\Pi(\delta, \delta_c, S)$
- Multiplicity function obtained from the first-crossing rate $\dot{\Pi}(S) = dF/dS$

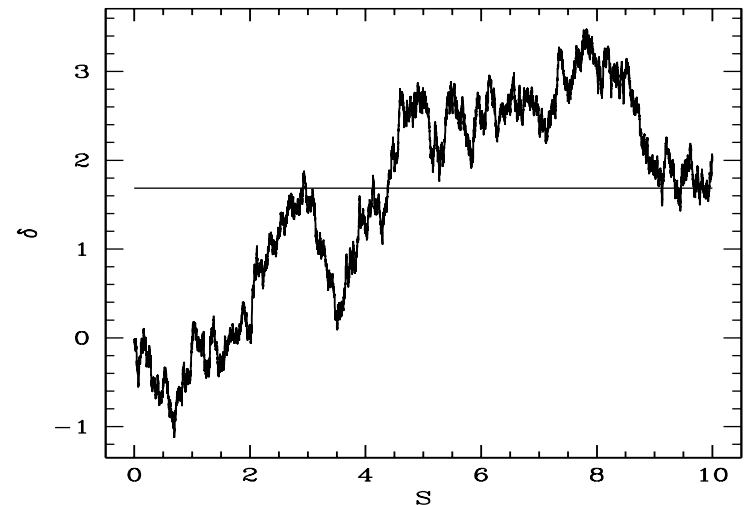
$$\int_0^S F(S) dS = 1 - \int_0^{\delta_c} P(d, d_c, S) dd \quad \longrightarrow \quad \frac{dF}{dS} = - \frac{\dot{\Pi}(d_c)}{\dot{\Pi}(S)} \int_0^{\delta_c} P(d, d_c, S) dd$$

Cloud-in-cloud: $\lim_{S \rightarrow \infty} P(d, d_c, S) = 0$

Sharp-k filter: $\tilde{W}(k, R) = q(1/R - k)$

- Markovian random walks

$$\frac{\dot{\Pi}(d)}{\dot{\Pi}(S)} = h(S) \quad \text{with} \quad \begin{aligned} \langle h(S) \rangle &= 0 \\ \langle h(S)h(S) \rangle &= d_D(S - S) \end{aligned}$$



Extended Press-Schechter

Fokker-Planck Equation:

$$\frac{\partial P}{\partial S} = \frac{1}{2} \frac{\partial^2 P}{\partial d^2} \quad \text{with} \quad \begin{aligned} P(d, 0) &= d_D(d) \\ P(d_c, S) &= 0 \end{aligned}$$

Solution:

$$P(d, S) = \frac{1}{\sqrt{2\rho S}} e^{-d^2/(2S)} - e^{-(2d_c-d)^2/(2S)} \quad \text{for } d < d_c$$

Multiplicity Function:

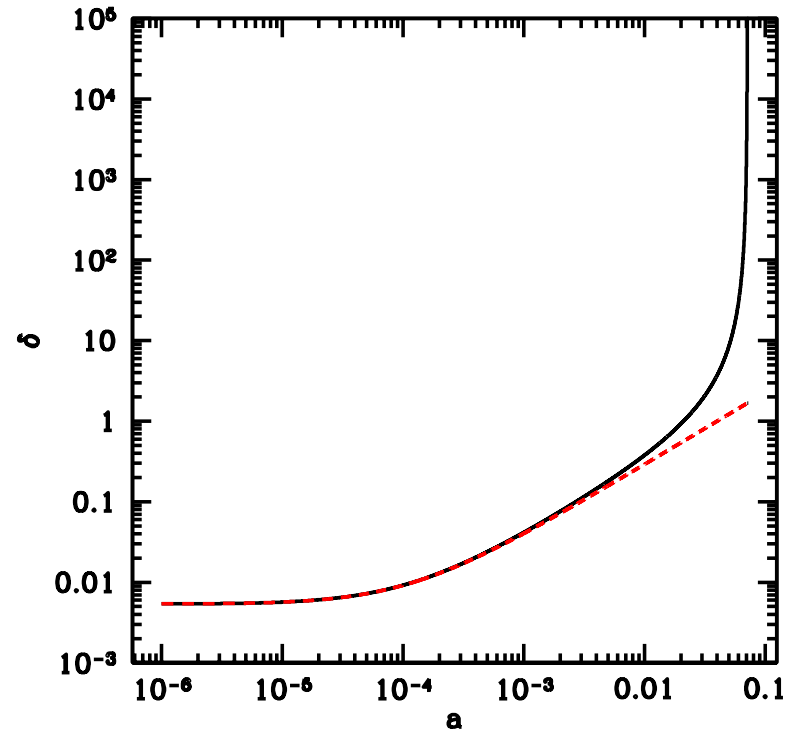
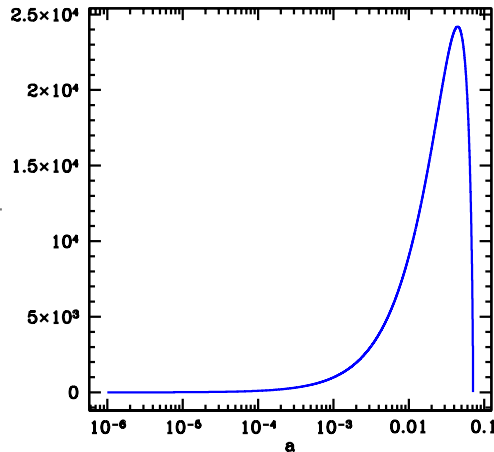
$$\frac{dF}{dS} = - \int_0^{d_c} P(d, d_c, S) dd \quad \longrightarrow \quad f_{EPS}(S) = \sqrt{\frac{2}{\rho}} \frac{d_c}{S} e^{-d_c^2/(2S^2)}$$

Halo Collapse Model

Spherical Collapse (Gunn & Gott, 1973)

- Top-hat perturbation in FRW background, $y=R/R_i$
- Dynamics independent of R_i

$$\ddot{y} = -\frac{4}{3} \rho G \bar{r}_m^j (1 + d_m^j) \frac{1}{y^2}$$



$$1 + d_m = (1 + d_m^j) y^3 \frac{\partial a \ddot{0}^3}{\partial a_j \ddot{0}}$$

Non-Spherical Halo Collapse

Ellipsoidal Collapse

- Initial Gaussian fluctuations are non-spherical (Doroshkevich, 1970)
- Ellipsoidal halos collapse and shear

$$\frac{d^2 a_i}{dt^2} = \frac{8}{3} \pi G \bar{\rho}_\Lambda a_i - 4 \pi G \bar{\rho}_m a_i \left[\frac{1}{3} + \frac{\Delta(t)}{3} + \frac{b'_i(t)}{2} \Delta(t) + \lambda'_i(t) \right]$$
$$b'_i = -\frac{2}{3} + a_1 a_2 a_3 \int_0^\infty \frac{d\tau}{(a_i^2 + \tau) \prod_{m=1}^3 (a_m^2 + \tau)^{1/2}}$$
$$\lambda_1 = \frac{\delta}{3} (1 - 3e + p)$$
$$\lambda_2 = \frac{\delta}{3} (1 - 2p)$$
$$\lambda_3 = \frac{\delta}{3} (1 + 3e + p)$$

- Dynamics dependent of initial size of the collapsing region
- Critical Overdensity is mass dependent (e.g. Eisenstein & Loeb, 1995)

“Fuzzy” Barrier

Stochastic Barrier

- Ellipsoidal parameters are random variables with characteristic probability distribution

- e.g. for a Gaussian density field

$$g(e, p | \delta) = \frac{1125}{\sqrt{10\pi}} e(e^2 - p^2) \left(\frac{\delta}{\sigma}\right)^5 \exp\left[-\frac{5}{2} \frac{\delta^2}{\sigma^2} (3e^2 + p^2)\right]$$

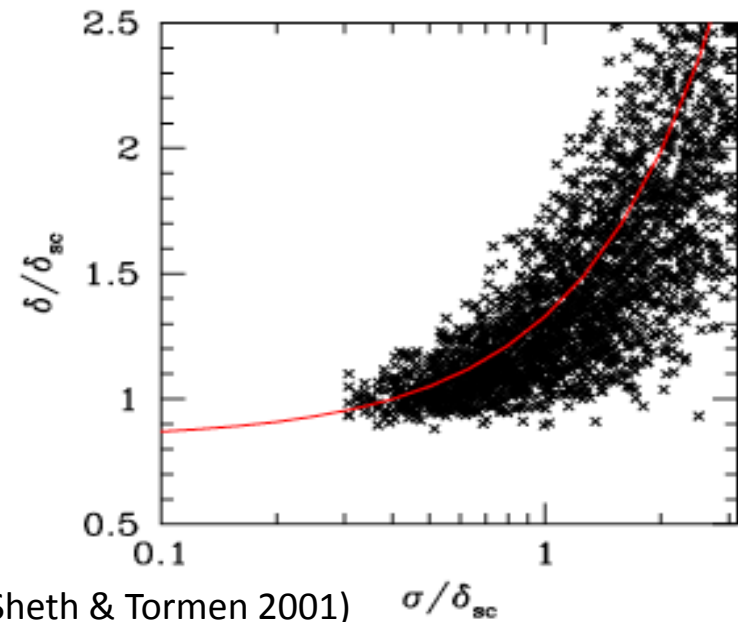
- Density threshold is a random variable

- e.g. $\langle B(S) \rangle = \delta_c [1 + \beta (S/S_*)^\nu]$

(Sheth, Mo & Tormen 2001)

- Stochastic barrier model: specify the moments of barrier's PDF

$\langle B(S) \rangle$ & $\langle (B(S) - \langle B(S) \rangle)^2 \rangle, \dots$



Stochastic Barrier and Excursion Set

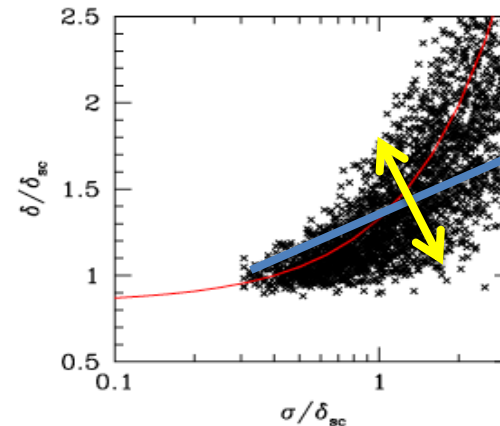
Non-Spherical Collapse:

- Diffusive Drifting Barrier $\langle B(S) \rangle = d_c + b S$ $\langle [B(S) - \langle B(S) \rangle]^2 \rangle^{1/2} = \sqrt{D_B S}$

β = rate of average deviation from spherical collapse

D_B = scatter of the collapse condition around mean (Maggiore & Riotto 2010b)

- Introduce: $Y = B - \delta$

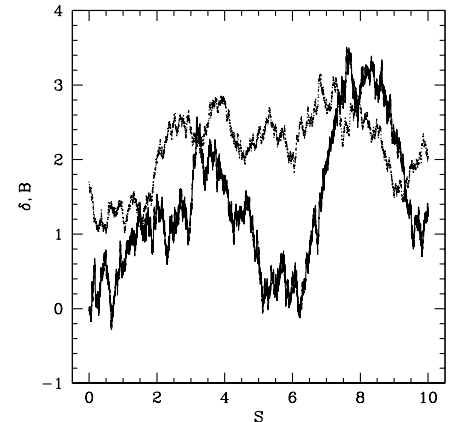


Sharp-k filter case:

$$\frac{\partial Y}{\partial S} = b + h(S)$$

$$\langle h(S) \rangle = 0$$

$$\langle h(S)h(S) \rangle = (1 + D_B)d_D(S - S)$$



Langevin & Fokker-Planck Equations

Generic Gaussian Random Walk:

$$\frac{\partial Y}{\partial S} = h(S) \quad \text{with} \quad \begin{aligned} \langle h(S) \rangle &= A(Y, S) \\ \langle h(S)h(S) \rangle &= B(Y, S) \end{aligned}$$

Probability Distribution Obeys:

$$\frac{\partial P}{\partial S} = -\frac{\partial}{\partial Y} [A(Y, S)P(Y, S)] + \frac{1}{2} \frac{\partial^2}{\partial Y^2} [B(Y, S)P(Y, S)]$$

$$\frac{\partial P}{\partial S} = -b \frac{\partial P}{\partial Y} + \frac{1 + D_B}{2} \frac{\partial^2 P}{\partial Y^2}$$

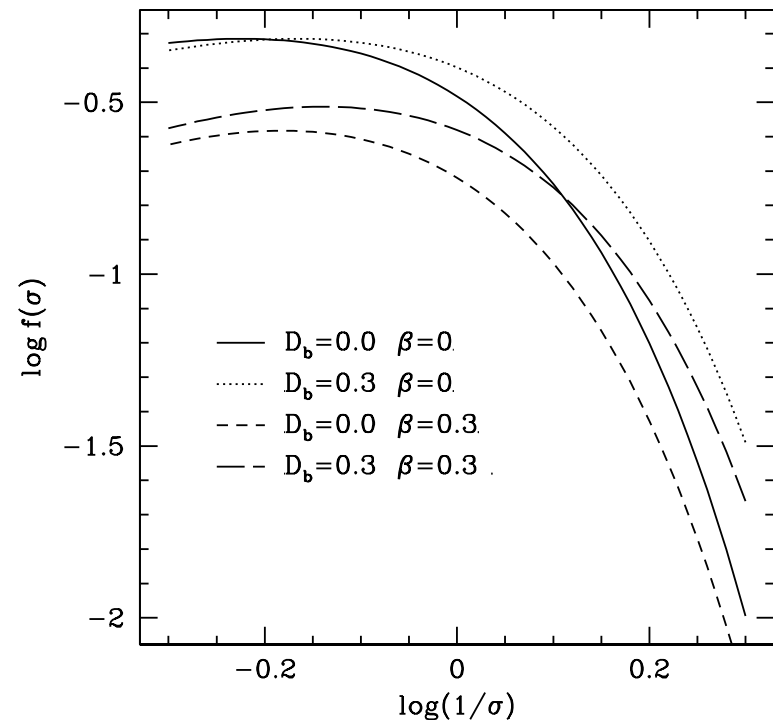
$$P(Y, 0) = d_D(Y - d_C)$$

$$P(0, S) = 0$$

$$P(Y, S) = \frac{e^{\frac{b}{1+D_B}(Y-Y_0-bS^2)}}{\sqrt{2\rho S(1+D_B)}} e^{-\frac{(Y-Y_0)^2}{2S(1+D_B)}} - e^{-\frac{(Y+Y_0)^2}{2S(1+D_B)}}$$

Multiplicity Function:

$$f(S) = \sqrt{\frac{2}{\rho}} \frac{d_C}{S\sqrt{1+D_B}} e^{-\frac{(d_C+bS^2)^2}{2S^2(1+D_B)}}$$



Filter Function and Halo Mass Definition

Mass and smoothing scale: $M(R) = \bar{\rho} V(R)$ with $V(R) = \int d^3x W(x, R)$

- Unambiguously define only for sharp-x filter:

$$V(R) = \int d^3x W(x, R) = 4/3 \rho R^3$$

- Generic filters define M up to an integration constant
- Sharp-k leaves M undefined

$$V(R) = 12 \rho R^3 \int_0^\pi du \frac{\sin u}{u} - \cos u$$

- Sharp-x leads to correlated random walks since

$$\tilde{W}(k, R) = 3 \frac{\sin(kR) - (kR)\cos(kR)}{(kR)^3}$$

Inaccuracies EPS result

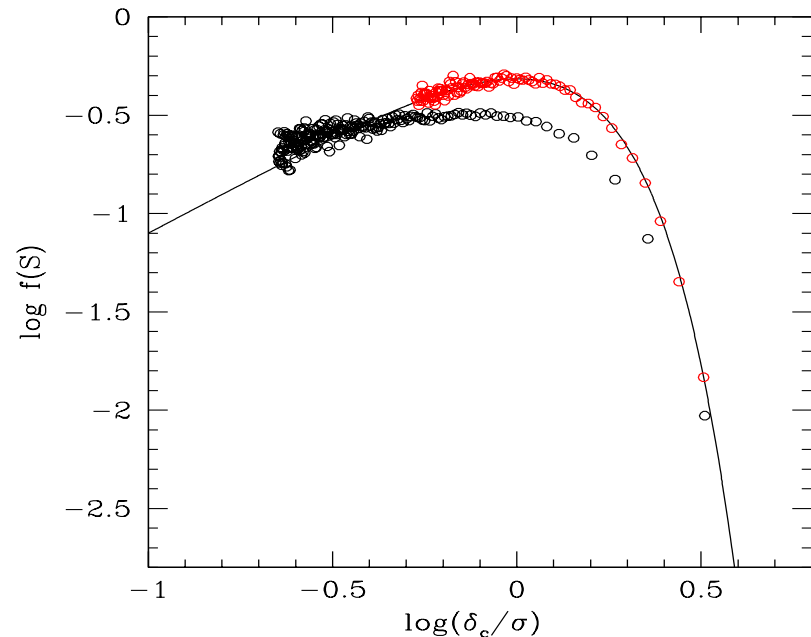
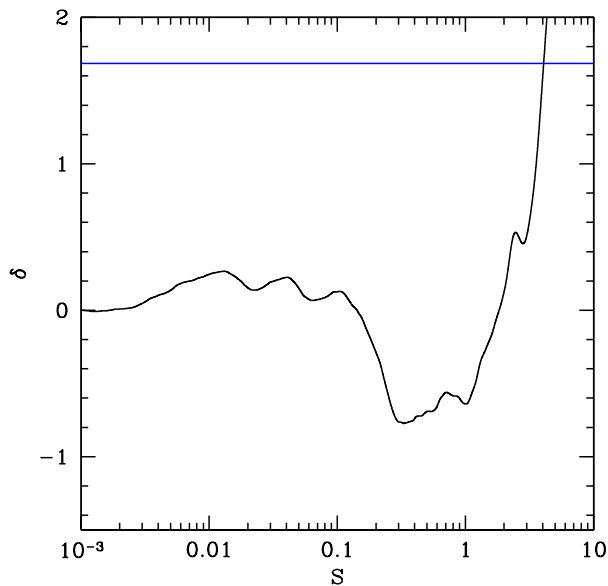
Langevin Equation:

$$\frac{\mathbb{1}d}{\mathbb{1}\ln k} = Q(\ln k) \tilde{W}(k, R)$$

$$\langle Q(\ln k) \rangle = 0$$

$$\langle Q(\ln k) Q(\ln k') \rangle = D^2(k) d_D (\ln k - \ln k')$$

Spherical Collapse Case:



Correlation Function

(Maggiore & Riotto 2010a)

Generic Filter:

$$\langle d[R(\mathbf{S})]d[R(\mathbf{S})] \rangle = \frac{1}{2\rho^2} \int_0^\infty dk k^2 P(k) T^2(k) \tilde{W}[k, R(\mathbf{S})] \tilde{W}[k, R(\mathbf{S})]$$

Sharp-k Filter:

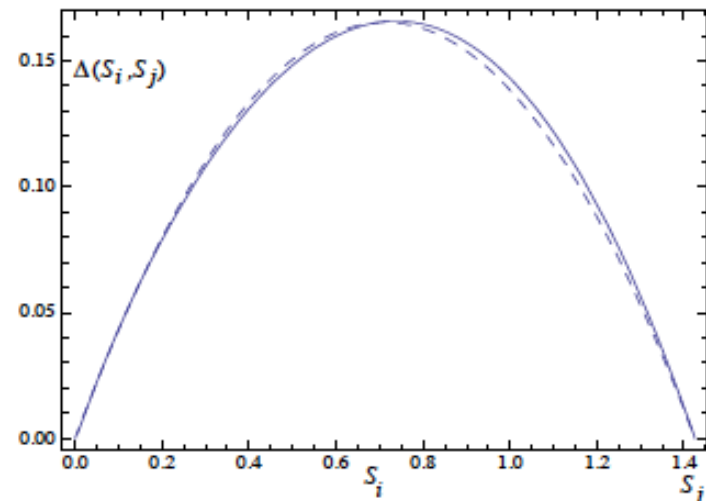
$$\langle d(\mathbf{S})d(\mathbf{S}) \rangle = \int_0^S ds \int_0^S ds' \langle h(s)h(s') \rangle = \min(S, S')$$

Introduce:

$$D(S, S') = \langle d(\mathbf{S})d(\mathbf{S}') \rangle - \min(S, S')$$

For LCDM power-spectrum:

$$D(S, S') @ k \frac{S(S' - S)}{S} \quad \text{where } \kappa \cong 0.47$$



Path-Integral Approach to Excursion Set

(Maggiore & Riotto 2010a)

Discrete Random Walks

- Trajectory over a discrete “time” interval $\{Y_0, Y_1, \dots, Y_n\}$ with $S_k = k \varepsilon$ and $k=1, \dots, n$

Ensemble Probability Density

$$p(Y_0, \dots, Y_n, S_n) = \langle d_D[Y(S_1) - Y_0] \times \dots \times d_D[Y(S_n) - Y_{n-1}] \rangle = \int D Y e^{i \hat{a} / \varepsilon Y} \left\langle e^{-i \hat{a} / \varepsilon Y(S)} \right\rangle$$

Partition function

$$e^Z = \left\langle e^{-i \hat{a} / \varepsilon Y(S)} \right\rangle \quad \text{with} \quad Z = \sum_{p=1}^{\infty} \frac{(-i)^p}{p!} \hat{a}^p \dots \hat{a}^p / \varepsilon^{i_1} \dots / \varepsilon^{i_p} \left\langle Y(S_{i_1}) \dots Y(S_{i_p}) \right\rangle_c$$

Connected Correlators

$$\langle Y(S) \rangle_c \equiv \bar{B}(S) = d_c + b S$$

$$\langle Y(S) Y(S_j) \rangle_c = (1 + D_B) \min(S, S_j) + D(S, S_j)$$

κ -expansion around Markovian solution

(Maggiore & Riotto 2010a)

Probability Distribution

$$\frac{dF}{dS} = -\frac{\mathcal{H}}{\mathcal{H}S_0} \int_0^{\mathcal{H}} P_{RW}(Y, Y_0, S) dY$$

$$P_e(Y_0, Y_n, S_n) = \int_0^{\mathcal{H}} dY_1 \dots \int_0^{\mathcal{H}} dY_{n-1} p(Y_0, \dots, Y_n, S_n)$$

Expansion to $O(\kappa)$

$$P_e(Y_0, Y_n, S_n) = \int_0^{\mathcal{H}} dY_1 \dots \int_0^{\mathcal{H}} dY_{n-1} \int D\mathcal{Y} \left(1 - \frac{1}{2} \sum_{i,j} \mathcal{H}_i \mathcal{H}_j D_{ij} \right) e^{i \sum_k \mathcal{H}_k [Y_k - \bar{B}_k]} e^{-i \sum_{n,m} \mathcal{H}_n \mathcal{H}_m A_{nm}}$$

Markovian solution and non-Markovian corrections

$$P_e(Y_0, Y_n, S_n) = P_e^M(Y_0, Y_n, S_n) + P_e^{K(1)}(Y_0, Y_n, S_n)$$

Markovian solution & Chapman-Kolmogorov

$$P_e^M(Y_0, Y_n, S_n) = \int_0^{\infty} dY_1 \dots \int_0^{\infty} dY_{n-1} p_0(Y_0, \dots, Y_n, S_n)$$

Markovian Density: $p_0(Y_0, \dots, Y_n, S_n) = \int_0^{\infty} D\mathbf{Y} e^{i\mathbf{a}^T \mathbf{Y} / k [Y_k - \bar{B}_k] - i\mathbf{a}^T \mathbf{Y} / m A_{nm}}$

$$p_0(Y_0, \dots, Y_n, S_n) = \frac{1}{[2pe(1 + D_B)]^{\frac{n}{2}}} e^{-\frac{1}{2e(1+D_B)} \sum_{i=1}^{n-1} [(Y_{i+1} - Y_i) - (\bar{B}_{i+1} - \bar{B}_i)]^2}$$

with $A_{ij} = \min(i, j)$

$$= y_e(DY) p_0(Y_0, \dots, Y_{n-1}, S_{n-1}) \quad \text{with} \quad y_e(DY) = \frac{1}{\sqrt{2pe(1 + D_B)}} e^{-\frac{(DY - be)^2}{2e(1+D_B)}}$$

Chapman-Kolmogorov: $P_e^M(Y_0, Y_n, S_n) = \int_0^{\infty} dY_{n-1} y_e(DY) P_e^M(Y_0, Y_{n-1}, S_{n-1})$

- In the continuous limit and developing RHS in $S+\varepsilon$ and LHS in $Y-\Delta Y$ we recover:

$$\frac{\mathbb{P} P_{e=0}^M}{\mathbb{P} S} = -b \frac{\mathbb{P} P_{e=0}^M}{\mathbb{P} Y} + \frac{1 + D_B}{2} \frac{\mathbb{P}^2 P_{e=0}^M}{\mathbb{P} Y^2}$$

Memory and Memory-of-Memory Terms

First Order Corrections:

$$P_e^{k(1)}(Y_0, Y_n, S_n) = P_e^m(Y_0, Y_n, S_n) + P_e^{m-m}(Y_0, Y_n, S_n)$$

Memory:

$$P_e^m(Y_0, Y_n, S_n) = - \sum_{i=1}^{n-1} D_{in} \partial_n \left[P_e^{M,f}(Y_0, 0, S_i) P_e^{M,f}(0, Y_n, S_n - S_i) \right]$$

Memory-of-Memory:

$$P_e^{m-m}(Y_0, Y_n, S_n) = \sum_{i < j} D_{ij} \left[P_e^{M,f}(Y_0, 0, S_i) P_e^{M,f}(0, 0, S_j - S_i) P_e^{M,f}(0, Y_n, S_n - S_j) \right]$$

- Markovian solution around the barrier $P_e^{M,f}$

Continuous Limit: $\sum_{i=1}^{n-1} \rightarrow \lim \frac{1}{e} \int_0^S dS_i$ & $\sum_{i < j} \rightarrow \lim \frac{1}{e^2} \int_0^S dS_i \int_{S_i}^S dS_j$

Corrections to Mass Function

Memory

$$f_1^m(s) = -2s^2 \frac{kY_0}{(1+D_B)^2} \frac{1}{s} \int_0^\infty dY_n \left[\frac{Y_n}{s} e^{\frac{b}{1+D_B}(Y_n - Y_0 - b s^2)} \operatorname{Erfc} \left(\frac{Y_0 + Y_n}{\sqrt{2s(1+D_B)}} \right) \right] = 0$$

Memory-of-Memory

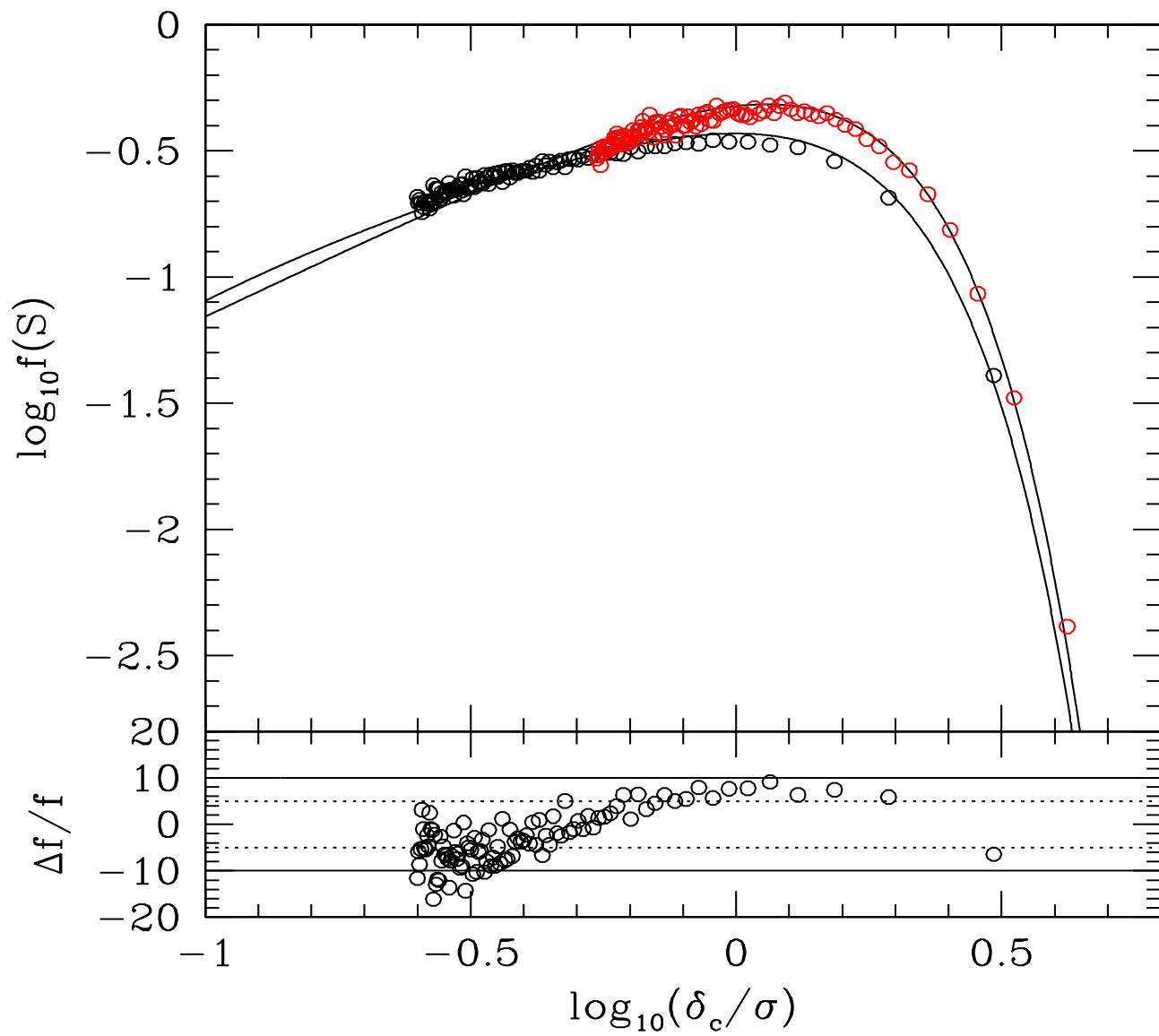
$$f_{1,\beta=0}^{m-m}(\sigma) = -\tilde{\kappa} \frac{\delta_c}{\sigma} \sqrt{\frac{2a}{\pi}} \left[e^{-\frac{a\delta_c^2}{2\sigma^2}} - \frac{1}{2} \Gamma \left(0, \frac{a\delta_c^2}{2\sigma^2} \right) \right]$$

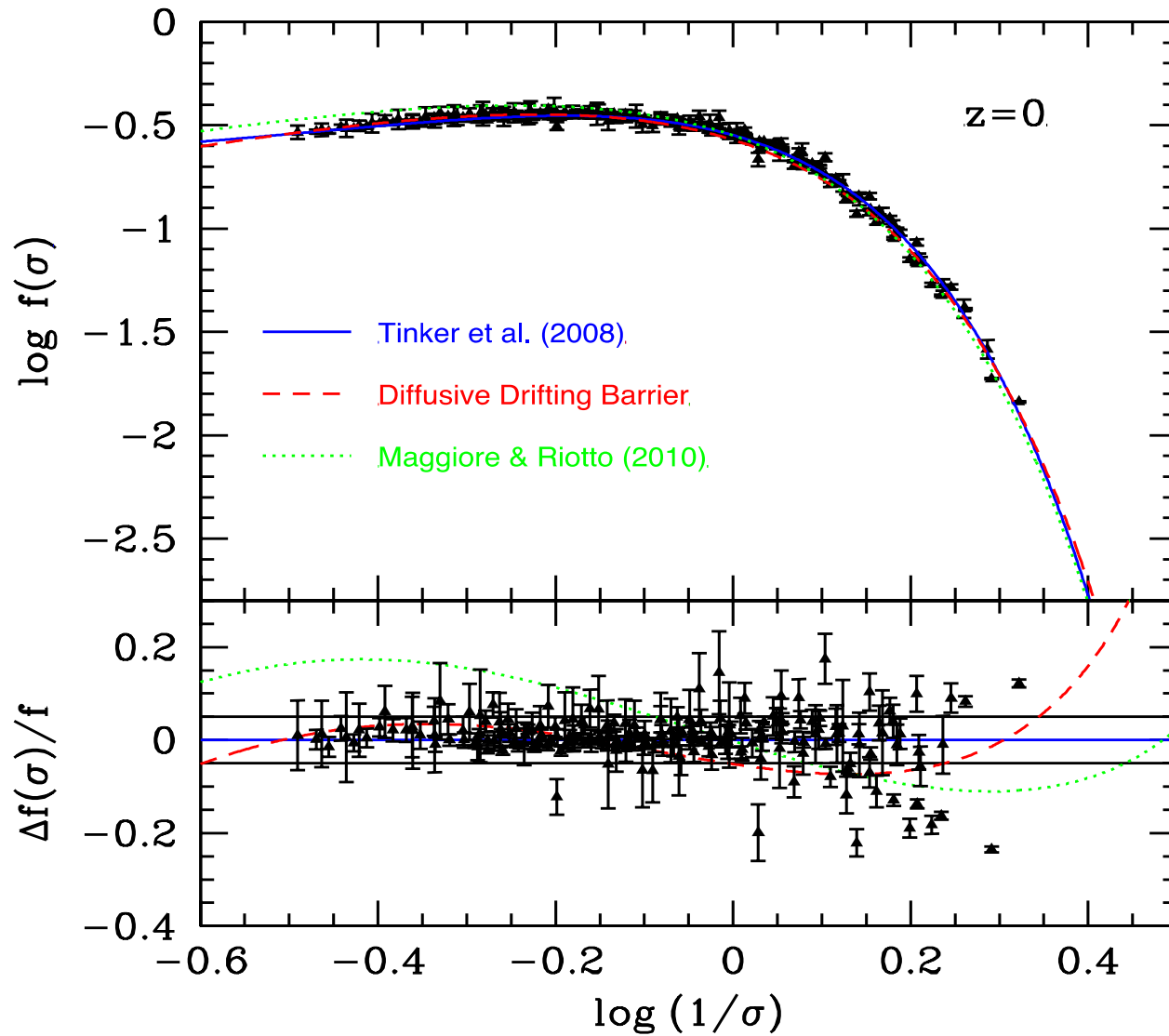
$$f_{1,\beta^{(1)}}^{m-m}(\sigma) = -\beta a \delta_c \left[f_{1,\beta=0}^{m-m}(\sigma) + \tilde{\kappa} \operatorname{Erfc} \left(\frac{\delta_c}{\sigma} \sqrt{\frac{a}{2}} \right) \right]$$

$$a = \frac{1}{1+D_B}$$

$$f_{1,\beta^{(2)}}^{m-m}(\sigma) = \beta^2 a \delta_c \tilde{\kappa} \left\{ a \delta_c \operatorname{Erfc} \left(\frac{\delta_c}{\sigma} \sqrt{\frac{a}{2}} \right) + \right. \\ \left. + \sigma \sqrt{\frac{a}{2\pi}} \left[e^{-\frac{a\delta_c^2}{2\sigma^2}} \left(\frac{1}{2} - \frac{a\delta_c^2}{\sigma^2} \right) + \frac{3}{4} \frac{a\delta_c^2}{\sigma^2} \Gamma \left(0, \frac{a\delta_c^2}{2\sigma^2} \right) \right] \right\}$$

$$\tilde{\kappa} = k a$$





Conclusions

- Path-Integral formulation of Excursion Set theory and Halo Collapse model
- Predicts barrier cosmology dependence from Ellipsoidal Collapse Model
- Extension to models beyond CDM
- Halo forms mostly on initial density peaks and not on random points: how accurate can the barrier model be?